

# Optimization Algorithms

## Weekly Exercise 3

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### 1 Gauss-Newton basics

- a) Let  $f(x) = \|\phi(x)\|^2$  be a sum-of-squares cost for the features  $\phi : \mathbb{R}^n \rightarrow \mathbb{R}^d$ . Derive the Gauss-Newton approximation  $\nabla^2 f(x) \approx 2J(x)^\top J(x)$  from a linear approximation (first order Taylor) of features  $\phi$ , with the Jacobian  $J(x) = \frac{\partial}{\partial x} \phi(x)$ .
- b) Show that for any vector  $v \in \mathbb{R}^n$  the matrix  $vv^\top$  is symmetric and semi-positive-definite.<sup>1</sup> Based on this, argue that the Gauss-Newton approximation  $J(x)^\top J(x)$  is also symmetric and semi-positive-definite.

### 2 Conjugate Gradient

The conjugate gradient methods initialized  $\delta_0 = g = -\nabla f(x_0)$  and then iterates the following steps:

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1: $\alpha \leftarrow \operatorname{argmin}_\alpha f(x + \alpha\delta)$	<i>// exact line search</i>
2: $x \leftarrow x + \alpha\delta$	
3: $g' \leftarrow g, g = -\nabla f(x)$	<i>// store old and compute new gradient</i>
4: $\beta \leftarrow \max \left\{ \frac{g'^\top (g - g')}{g'^\top g'}, 0 \right\}$	
5: $\delta \leftarrow g + \beta\delta$	<i>// conjugate descent direction</i>

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Consider the quadratic cost function  $f(x) = \frac{1}{2}x^\top Ax + b^\top x + c$  with  $A = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$ ,  $b = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$  and  $c = 0$  whose minimum is achieved at  $x^* = (0, 0)$ .

- a) Compute, by hand, two iterations of the conjugate gradient descent from  $x_0 = (1, 1)$  and from  $x_0 = (-1, 2)$ , respectively.
- b) Show that the first and second descent directions are  $A$ -orthogonal, i.e.,  $\delta_0^\top A \delta_1 = 0$ .

### 3 Solve by Sketch and check KKT

In this exercise, for each of the following problems do the following:

- Sketch the problem on paper and, without much maths, figure out where the optimum  $x^*$  is.
- State which constraints are active at  $x^*$ .
- Compute (by hand) the gradient  $\nabla f$  and gradients  $\nabla g_i, \nabla h_j$  of active constraints at  $x^*$ .
- Identify dual parameters  $\lambda_i, \kappa_j$  so that the stationarity (1st KKT) condition holds at  $x^*$ .

- a) A 1D problem:

$$\min_{x \in \mathbb{R}^1} x \quad \text{s.t.} \quad \sin(x) = 0, \quad x^2/4 - 1 \leq 0$$

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<sup>1</sup>A matrix  $A \in \mathbb{R}^{n \times n}$  is semi-positive-definite simply when for any  $x \in \mathbb{R}^n$  it holds  $x^\top Ax \geq 0$ . Intuitively:  $A$  might be a metric as it “measures” the norm of any  $x$  as positive. Or: If  $A$  is a Hessian, the function is (locally) convex.

b) 2D problems: (Note that  $1^\top x = \sum_i x_i$  is a simple linear cost.)

$$\min_{x \in \mathbb{R}^2} 1^\top x \quad \text{s.t.} \quad |x|^2 - 1 \leq 0$$

c)

$$\min_{x \in \mathbb{R}^2} 1^\top x \quad \text{s.t.} \quad |x|^2 - 1 \leq 0, \quad -x_1 \leq 0$$

d)

$$\min_{x \in \mathbb{R}^2} 1^\top x \quad \text{s.t.} \quad x^2 - 1 \leq 0, \quad x_2^2 - x_1 \leq 0$$