

# Maths for Intelligent Systems

## Exercise 8

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### 1 Lagrangian and dual function

(Taken roughly from ‘Convex Optimization’, Ex. 5.1)

Consider the optimization problem

$$\min_x x^2 + 1 \quad \text{s.t.} \quad (x - 2)(x - 4) \leq 0$$

with variable  $x \in \mathbb{R}$ .

- Derive the optimal solution  $x^*$  and the optimal value  $p^* = f(x^*)$  by hand.
- Write down the Lagrangian  $L(x, \lambda)$ . Plot (using gnuplot or so)  $L(x, \lambda)$  over  $x$  for various values of  $\lambda \geq 0$ . Verify the lower bound property  $\min_x L(x, \lambda) \leq p^*$ , where  $p^*$  is the optimum value of the primal problem.
- Derive the dual function  $l(\lambda) = \min_x L(x, \lambda)$  and plot it (for  $\lambda \geq 0$ ). Derive the dual optimal solution  $\lambda^* = \operatorname{argmax}_\lambda l(\lambda)$ . Is  $\max_\lambda l(\lambda) = p^*$  (strong duality)?

### 2 Optimize a constrained problem

Consider the following constrained problem

$$\min_x \sum_{i=1}^n x_i \quad \text{s.t.} \quad g(x) \leq 0 \tag{1}$$

$$g(x) = \begin{pmatrix} x^\top x - 1 \\ -x_1 \end{pmatrix} \tag{2}$$

- First, assume  $x \in \mathbb{R}^2$  is 2-dimensional, and draw on paper what the problem looks like and where you expect the optimum.
- Find the optimum analytically using the Lagrangian. Here, assume that you know apriori that all constraints are active! What are the dual parameters  $\lambda = (\lambda_1, \lambda_2)$ ?

Note: Assuming that you know a priori which constraints are active is a huge assumption! In real problems, this is the actual hard (and combinatorial) problem. More on this later in the lecture.

c) Implement a simple the Log Barrier Method. Tips:

- Initialize  $x = (\frac{1}{2}, \frac{1}{2})$  and  $\mu = 1$
- First code an inner loop:
  - In each iteration, first compute the gradient of the log-barrier function. Recall that

$$F(x; \mu) = f(x) - \mu \sum_i \log(-g_i(x)) \tag{3}$$

$$\nabla F(x; \mu) = \nabla f - \mu \sum_i (1/g_i(x)) \nabla g_i(x) \tag{4}$$

- Then perform a backtracking line search along  $-\nabla F(x, \mu)$ . In particular, backtrack if a step goes beyond the barrier (where  $g(x) \not\leq 0$  and  $F(x, \mu) = \infty$ ).

- Iterate until convergence; let's call the result  $x^*(\mu)$ . Further, compute  $\lambda^*(m) = -(\mu/g_1(x), \mu/g_2(x))$  at convergence.
- Decrease  $\mu \leftarrow \mu/2$ , recompute  $x^*(\mu)$  (with the previous  $x^*$  as initialization) and iterate this.

Does  $x^*$  and  $\lambda^*$  converge to the expected solution?

Note: The path  $x^*(\mu) = \operatorname{argmin}_x F(x; \mu)$  (the optimum in dependence of  $\mu$ ) is called *central path*.