

# Mathematics for Intelligent Systems

## Lecture 1 Homework

(Linear Algebra I: Vector Spaces and Bases)

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### Abstract

This homework explores coordinate-free definitions of vector spaces, and coordinate-ful representations which arise only once a basis is chosen.

## 1 Problem 1

- Find 3 interesting examples of vector spaces that we haven't covered in class. What are their dimensions? What bases are commonly used to represent them? (It's okay to look this up in a textbook or online—just find interesting examples.)
- Come up with one example of a set which is *almost* a vector space, i.e. it satisfies some of the core requirements of a vector space, but not all.

## 2 Problem 2

Consider a collection of functions  $\mathcal{V}$  defined by

$$f(x) = \alpha_0 + \alpha_1 x + \alpha_2 x^2 + \dots + \alpha_n x^n \quad (1)$$

where  $x \in \mathbb{R}$  and  $\alpha_i \in \mathbb{R}$  for each  $i = 0, \dots, n$ .

- Is this collection of functions a vector space? Why?
- Consider the bases

$$\mathcal{B}_1 = \{1, x, x^2, \dots, x^n\}$$

and

$$\mathcal{B}_2 = \{1, 1+x, 1+x+x^2, \dots, 1+x+\dots+x^n\}.$$

Let  $f(x) = 1+x+x^2+x^3$ . (This function  $f$  is a vector in the vector space  $\mathcal{V}$ , so from here on out we refer to it as a vector rather than a function.) What are the coefficients of this vector in terms of  $\mathcal{B}_1$  and  $\mathcal{B}_2$ ?

- Consider the set of all *even* functions. Is this a Vector space? If so, define 3 different bases which span the entire space.